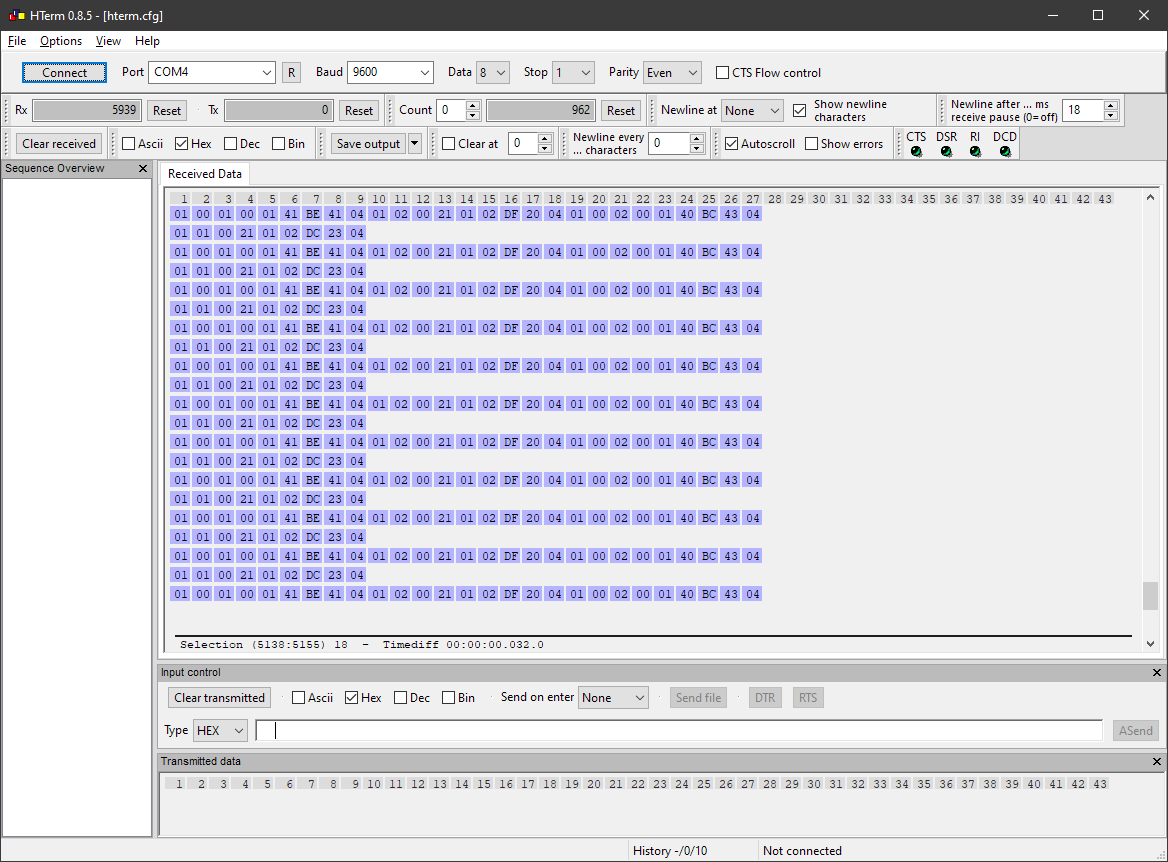
This is a short recording of the polling of Novotec. What you can see here are two things:

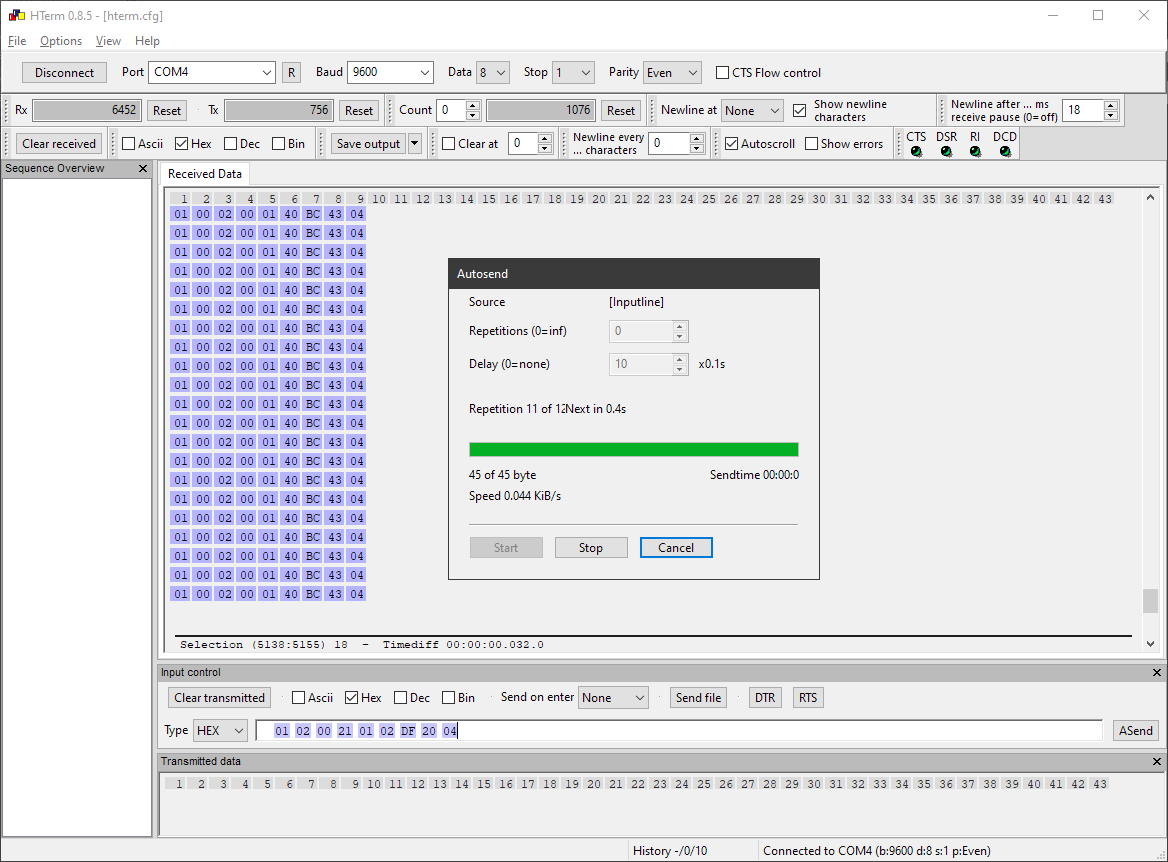
The Bluebox replies after 10 ms, therefore, there is no new line. The Tiris is app. 10 times slower.

The Tiris replies with status code 41 (INCOMPLETE), while the Bluebox replies with status code 40 (NO READ).

But this difference is probably meaningless.



Now I have split up the bus (no Novotec on the bus) and use the Autosend function of hterm for polling the Bluebox:



With this setting, I have started the video and triggered input 1 of the Bluebox. 3 data tags were present all the time on the antenna.